

Using Existing Modelica Models in Modeling with ModelicaML

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Introduction / Motivation

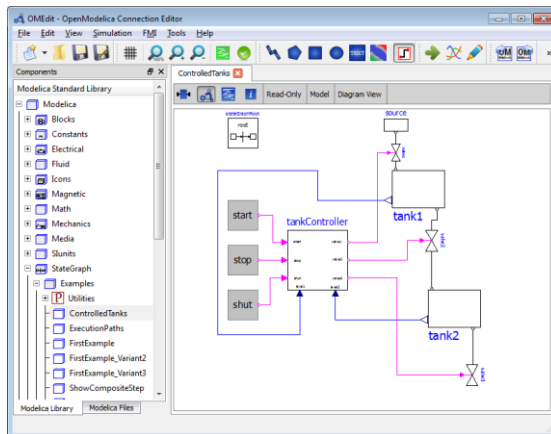
- ModelicaML integrates a subset of the UML and the Modelica language
- vVDR (Virtual Verification of Designs against Requirements) is a method that enables a model-based design verification against requirements
- vVDR is supported in ModelicaML

- How to enable the **usage of existing Modelica models in ModelicaML?**
 - E.g. Libraries or models that are created using Modelica tools

Typical Usage Scenario

- Use a **Modelica** tool to:
 - Develop system design models
 - Simulate models
- Use a **ModelicaML** tool to:
 - Import Modelica models
 - Formalize/model requirements, model test / verification scenarios
 - Compose verification models, simulate verification models and generate reports
 - Visualize dependencies using UML graphical notation (e.g. inheritance)

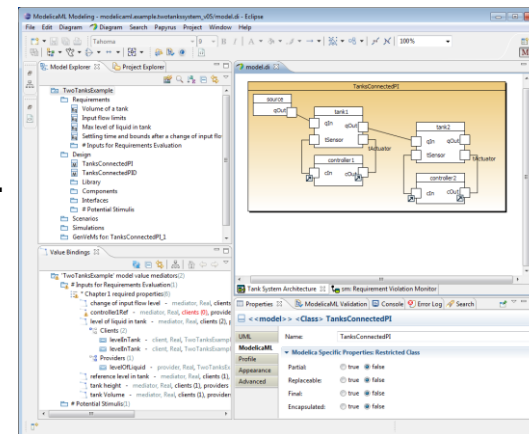
Modelica Tool



Import/sync.



ModelicaML Tool



Concept

- Modelica models can be stored in the “**code-sync**” folder in ModelicaML Eclipse projects
- A dedicated viewer allows the browsing of the contained Modelica models
- A dedicated helper translates Modelica models from the “code-sync” into ModelicaML and mark them as “**proxies**”
 - Restriction: the top level Modelica models must be packages and not have any import or extends relations
- The translated models can be **synchronized** with the ModelicaML proxies whenever the Modelica models have been modified
- When synchronizing any identifiable element is updated, other are re-created (references will get lost)
- The created “proxies” can be used in ModelicaML models (i.e. referenced, instantiated)
- No code is generated from “proxies” classes
- For the simulation the code from both folders must be loaded
 - the generated ModelicaML model code from “**code-gen**” folder
 - and the code from the “**code-sync**” folder

Implementation

ModelicaML Modeling - modelicaml.example.usingModelicaModels/code-sync/ExistingModelicaCode.mo - Eclipse

File Edit Search Project Window Help

Correct Indentation Build project

Model Explorer Project Explorer

modelicaml.example.usingModelicaModels

- code-gen
- code-sync
 - ExistingModelicaCode.mo
- verification-gen
- model.di
- model.notation
- model.uml

Modelica Models

code-sync (1) - modelicaml.example.usingModelicaModels

- ExistingModelicaCode (12)
 - ActSignalIn (1)
 - ActSignalOut (1)
 - ReadSignalIn (1)
 - ReadSignalOut (1)
 - LiquidFlowIn (1)
 - LiquidFlowOut (1)
 - BaseController (7)
 - K: Real
 - T: Real
 - cIn: ExistingModelicaCode.ReadSignalIn
 - cOut: ExistingModelicaCode.ActSignalOut
 - ref: Real
 - error: Real
 - outCtr: Real
 - limitValue (4)
 - LiquidSource (2)
 - PIcontinuousController (2)
 - Tank (9)
 - TanksConnectedPI (5)

```

26
27 partial model BaseController
28   parameter Real K = 2 "Gain";
29   parameter Real T(unit = "s") = 10 "Time constant";
30   ReadSignalIn cIn "Input sensor level, connector";
31   ActSignalOut cOut "Control to actuator, connector";
32   parameter Real ref "Reference level";
33   Real error "Deviation from reference" level";
34   Real outCtr "Output control signal";
35 equation
36   error = ref - cIn.val;
37   cOut.act = outCtr;
38 end BaseController;
39
40 function limitValue
41   input Real pMin;
42   input Real pMax;
43   input Real p;
44   output Real pLim;
45 algorithm
46   pLim := if p>pMax then pMax
47           else if p<pMin then pMin
48           else p;
49 end limitValue;
50
51 model LiquidSource
52   LiquidFlowOut qOut;
53   //parameter Real flowLevel = 0.02;
54   input Real flowLevel = if time > 150 then 3*0.02 else 0.02;
55
56 equation
57   //qOut.lflow = if time > 150 then 3*flowLevel else flowLevel;
58   qOut.lflow = flowLevel;
59 end LiquidSource;
60
  
```

Live Demo

The screenshot displays the ModelicaML Modeling software interface. The main window shows a project explorer on the left and a model diagram on the right. The project explorer is titled "TwoTanksExample" and contains a folder "ExistingModelicaCode" with the following items:

- BaseController
- limitValue
- LiquidSource
- PIcontinuousController
- Tank
- TanksConnectedPI
- ActSignalIn
- ActSignalOut
- ReadSignalIn
- ReadSignalOut
- LiquidFlowIn
- LiquidFlowOut
- profileApplication (14)

The "Modelica Models" window at the bottom left shows a "code-sync" window with the following items:

- ExistingModelicaCode (12)
 - ActSignalIn (1)
 - ActSignalOut (1)
 - ReadSignalIn (1)
 - ReadSignalOut (1)
 - LiquidFlowIn (1)
 - LiquidFlowOut (1)
 - BaseController (7)
 - limitValue (4)
 - LiquidSource (2)
 - PIcontinuousController (2)
 - Tank (9)
 - TanksConnectedPI (5)

The main diagram, titled "ML_TanksConnectedPI", shows a block diagram of a two-tank system. It includes a "source" block with a "qOut" output, two "tank" blocks (tank1 and tank2), two "controller" blocks (controller1 and controller2), and two "tSensor" blocks. The diagram illustrates the flow of liquid between the tanks and the control loops for each tank.

OMC API Enhancements

- Queering of Modelica models using OMC CORBA API
- `getImportCount(M1)`, `getNthImport(M1, 1)`
- `getInitialAlgorithmCount(M1)` , `getNthInitialAlgorithm(M1, 1)`
- `getAlgorithmCount(M1)`, `getNthAlgorithm(M1, 1)`
- `getInitialEquationCount(M1)`, `getNthInitialEquation(M1, 1)`
- `getEquationCount(M1)` , `getNthEquation(M1, 1)`
- `getNthComponentCondition(M1, 1)`
- `isEnumeration(M1)`
- `getEnumerationLiterals(M1)`
- `isReplaceable(M1, "C1")`
- `getAnnotationCount(M1)`, `getNthAnnotationString(M1, 1)`
- In progress: `constrainedBy` and partial derivative function relations

Thank you for your attention!

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